Lecture Notes in Control and Information Sciences

Edited by M. Thoma and A. Wyner

86

Time Series and Linear Systems

Edited by Sergio Bittanti



copie con correctioni

Sergie Bittant

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PREFACE

Over the five past years, a stream of research at the Politecnico di Milano (Italy) has been in the methodology of modelling and identification of time series by means of linear systems. Several specialists of different backgrounds, including System and Control Theory, Statistics, Econometrics, Numerical Analysis, visited the Politecnico contributing with their talks to setting up a workshop on the subject. The train of ideas underlying this activity was to develop a system-theoretic point of view for the art of modelling.

This book is a partial report of such an activity. The various chapters are extended introductory papers overviewing important advanced topics in the field. They also constitute useful introductions to research directions of current interest.

The book is organized as follows. The first chapter is an introduction to the use of stochastic models in time series analysis. The problem of modelling is interpreted here as the problem of finding the linear model which is the best approximant for the data at hand. Among other things the use of criteria such as AIC or BIC is critically discussed. Moreover, the problem of determining a suitable rational transfer function approximation is studied as the problem of approximating the infinite Hankel matrix of the impulse response coefficients with a Hankel matrix of finite rank. Linear systems where all observed variables are subject to errors are considered in the second chapter. The motivation is that prejudicial causality assumtions can then be avoided. A new class of dynamic models

for time series is proposed in the third chapter. These models are based on the classical Factor Analysis approach, and are strictly related to the systems introduced in Chapter 2. The fourth chapter is devoted to the so called Minimum Description Length approach. A model is then judged by the number of binary digits with which it permits to encode the observed data. This leads to the notion of stochastic complexity of the data, as the shortest number of binary digits with which it permits to encode the observed data. Chapter 5 deals with systems with periodically time-varying coefficients, which can be used to describe seasonal time series. The attention focuses here on the basic structural properties of these systems, i.e. reachability, stabilizability and so on. The role played by these properties in the analysis of stochastic periodic systems is touched upon. Some numerical problems in linear system theory are considered in the sixth chapter. An extensive overview of the LU, QR, Shur and Singular Value Decomposition algorithms is provided. Then, the problem of computing the reachability subspace of a time-invariant system is studied. The last chapter is devoted to the discussion of some recent trends in Econometrics.

The volume can be used either as a textbook for monographic courses on the subject or as a reference book providing researchers with the main trends and perspectives in the field.

The editor expresses his sincere acknowledgment to the fellow authors for their most valuable contributions, as well as their care and patience in the preparation of the manuscripts. The support of the Centro di Teoria dei Sistemi of the National Research Council (C.N.R.) and that of the Ministry of Education (M.P.I.) is gratefully acknowldged.

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ABSTRACTS

<u>Chapter 1</u> TIME SERIES AND STOCHASTIC MODELS by E.J. Hannan

The basic concept of this paper is a linear system wherein an output y(t), of q components, is related to an input, u(t), of p components via a relation

$$y(t) = \sum_{0}^{\infty} W_{i} e(t-i) + \sum_{1}^{\infty} L_{i} u(t-i)$$

wherein the e(t) are the linear prediction errors for $y(t) - \Sigma L_i u(t-i)$. The methods of the paper are substantially valid when the system is truly linear in the sense that linear prediction is optimal, but may prove useful over a much wider range.

To bring the problem back to reasonable proportions the statistical methods are based on the approximation of the true structure by one wherein the matrix functions

$$W(z) = \Sigma W_{i} z^{-i}, L(z) = \Sigma L_{i} z^{-i}$$

are approximated by matrices of rational functions. A brief discussion is given of some basic theory relating to such an approximation process. It is necessary, in the approximation to choose the "order" of the approximant, i.e. effectively the maximum lags in the ARMAX model,

$$\begin{array}{ccc} h & h & h \\ \Sigma A_{i}Y(t-i) &= \Sigma B_{i}u(t-i) + \Sigma C_{i}e(t-i) \\ 0 & 1 & 0 \end{array}$$

to which the rational transfer function corresponds. Various algorithms are described that are basic in time series analysis and are then used to effect a solution to the problem of finding a suitable approximant. The main algorithm described does this by a Gauss-Newton iteration in which the order is redetermined at each iteration by a calculation recursive in the order.

Finally, on-line implementations of the algorithm are presented for the case where y(t) is scalar.

<u>Chapter 2</u> LINEAR ERRORS-IN-VARIABLES SYSTEMS by M. Deistler

Linear errors-in-variables (EV) systems, i.e. linear systems where all observed variables are subject to errors are considered. The statistical analysis of such systems turns out to be significantly more complicated compared to conventional errors in equations (e.g. ARMAX) systems. A good part of these complications arises from the fact that the transfer function of the system in the EV case, in general, is not uniquely determined from the second moments of the observations.

The paper is organized as follows: In section 2 some well known results concerning the static case are restated. In sections 3 - 5 the information about the transfer function contained in the (ensemble) second moments of the observations is analysed: In section 3 the set of all transfer functions

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corresponding to given second moments of the observations is described. Section 4 deals with the same problem when the system is a priori known to be causal and with the problem whether causality can be detected from the second moments of the observations. In section 5 conditions for identifiability are derived. Section 6 deals with conditions for identifiability using information coming from moments of order greater than two.

Chapter 3 A NEW CLASS OF DYNAMIC MODELS FOR STATIONARY TIME SERIES by G. Picci and S. Pinzoni

A new class of dynamic models for stationary time series is presented. They are a natural generalization of the wellknown linear Factor Analysis Models widely used in Statistics and Psychometrics. It is shown that the Factor Analysis Models of time series considered in this note reduce to (and to some extent clarify the structure of) Dynamic Errors-In-Variable Models discussed in the recent literature. They provide simple mathematical schemes for the identification of multivariate time series which avoid the unjustified introduction of a priori causality assumptions as for example subsumed by conventional ARMAX models.

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Chapter 4 PREDICTIVE AND NONPREDICTIVE MINIMUM DESCRIPTION LENGTH PRINCIPLES by J. Rissanen

This chapter presents in a tutorial manner the basic ideas behind the recently developed estimation principle, called Minimum Description Length principles. Briefly, a statistical model is judged by the number of binary digits with which it permits one to encode the observed data. The shortest code length available for models in a class is defined to be the stochastic complexity of the data. Depending on how the coding is done two kinds of stochastic complexities can be defined, the predictive and the nonpredictive ones, which for large samples tend to the same value. The stochastic complexity also sets a tight lower bound for the errors with which the data can be predicted. The model associated with the complexity involves estimates both of the number of the parameters and their values, which may be taken to incorporate all the statistical information that can be extracted from the data with the considered models. Hence, we may say that the fundamental problems in modeling are to calculate the stochastic complexity and the associated optimal model.

As applications we describe the calculation of the stochastic complexity of the data relative to the gaussian ARMA class of models, both in the single and the multiple input/output case.We illustrate with simulations the consistency of the associated estimates of the number of the parameters and the structures. We also describe how the prior knowledge about the parameters, as represented by their estimated values, can be taken advantage of. The feasibility of the scheme is demonstrated by simulations.

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<u>Chapter 5</u> DETERMINISTIC AND STOCHASTIC LINEAR PERIODIC SYSTEMS by S. Bittanti

The main results concerning the structural properties of linear periodic systems are reviewed. Both continuous-time and discrete-time systems are dealt with. By a comparison with time-invariant systems, five structural properties are discussed. Three of them are basic properties concerning the reachability and controllability subspaces. The fourth one concerns the length of the time interval required to perform the reachability and controllability transition. The modal (spectral) characterizations are presented as fifth property. The extended structural properties (i.e. stabilizability and detectability) are also dealt with. Finally, periodic stochastic systems are considered. The existence of a cyclostationary solution is investigated by analizing the appropriate periodic Lyapunov equation.

<u>Chapter 6</u> NUMERICAL PROBLEMS IN LINEAR SYSTEM THEORY by D. Boley and S. Bittanti

We discuss some numerical aspects in linear system theory.We start by showing the numerical algorithm to solve systems of linear equations and non-degenerate least squares problems.We then move on to an introduction to more sophisticated matrix decompositions, used to solve more sophisticated problems, and introduce the cincept of *backward error analysis* (Wilkinson, 1965). Among the decompositions we introduce

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name	form	used to obtain
LU (Gaussian Elimination)	A=LU	. solution of linear Equations . determinant
QR (orthogonal triangularization)	A=QR	 soln. to least Squares problem (linear non degenerate) soln. to linear Equations without need to pivot
Schur	A=QRQ	. Eigenvalues/vectors
Singular Value Decomposition (S.V.D.)	Α=ΡΣΟ΄	 Singular Values rank distance to singularity 2-norm of matrix 2-norm condition number

where P,Q denote orthogonal matrices

U,R			upper	triangular	matrices
L		н	lower	triangular	matrices
Σ	is	non	-negati	ive diagonal	L

In the last section we discuss some numerical aspects in linear system theory. The attention is focused on the problem of computing the controllable subspace of a time-invariant linear system. It is shown how some classical methods lead to numerical problems and give some recent results giving bounds on the errors in terms of results from these classical methods.

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<u>Chapter 7</u> SOME RECENT DEVELOPMENTS IN ECONOMETRICS by M. McAleer and M. Deistler

In this paper we discuss some of the main recent developments in econometrics: methods for specification search, in particular, diagnostic checking and specification testing; macroeconomic modelling and forecasting; and some models associated with empirical microeconomics.

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